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To cite this version:

HAL Id: hal-01666818
https://hal-mines-paristech.archives-ouvertes.fr/hal-01666818
Submitted on 18 Dec 2017

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Towards Compositional and Generative Tensor Optimizations

Adilla Susungi, Norman A. Rink, Jerónimo Castrillón, Immo Huismann, Albert Cohen, Claude Tadonki, Jörg Stiller and Jochen Fröhlich

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### Tensors in Computational Fluid Dynamics (CFD)
- Loop characteristics:
  - 3 to 4 dimensions nesting
  - Few iterations per dimension (e.g., 17 or 33 iterations)
- Type of computations:
  - Tensor contractions
  - Outer products
  - Element-wise multiplications
  - Computations on each element of a structured mesh

### Inverse Helmholtz

\[
t_{ijk} = \sum_{l,m,n} A_{kl}^{T} A_{jm}^{T} A_{il}^{T} \cdot u_{lmn} \\
p_{ijk} = D_{ij} \cdot t_{ijk} \\
v_{ijk} = \sum_{l,m,n} A_{kn} \cdot A_{jm} \cdot A_{il} \cdot p_{lmn}
\]

### Tensor Optimization Frameworks

- Domain-specific expressivity
- Flexible/Adaptive optimization heuristics
- Hidden and/or rigid optimization heuristics
- Generic expressivity
- Hidden and/or rigid optimization heuristics

### Related Work

- Different levels of expressiveness and control on optimizations
  - Flexible/adaptive
  - Hidden/rigid
- Specific
- Generic

### Optimizing CFD Kernels with Existing Tools

- Several limitations
- Few opportunities for adaptations

### Goal

- A cross-domain intermediate language for tensor optimizations

### Intermediate Language

- Modular constructs
- First-class citizens:
  - Arrays
  - Tensor operators
  - Loop iterators
  - Transformations

### Envisioned Tool

- Meta-programming
- Iterative search

### Search Space Exploration

- Evaluation order of tensor contractions
- Fusions
- Permutations
- Vectorization
- Collapsing
- Unrolling

### Inverse Helmholtz by Example

```plaintext
# Basic array declaration
A = array(2, double, [N, N])
u = array(3, double, [N, N, N])
D = array(3, double, [N, N, N])

# Transposition
At = vtranspose(A, 1, 2)

# Tensor contractions
tmp1 = contract(At, u, [2, 1])
tmp2 = contract(At, tmp1, [2, 2])
tmp3 = contract(At, tmp2, [2, 3])

# Element-wise multiplication
tmp4 = entrywise(D, tmp3)

# Tensor contractions
tmp5 = contract(A, tmp4, [2, 1])
tmp6 = contract(A, tmp5, [2, 2])

# Iterator declaration
i1 = iterator(0, N, 1)
i2 = iterator(0, N, 1)
i3 = iterator(0, N, 1)
i4 = iterator(0, N, 1)

# Association of iterators
build(D, [td1, td2, td3])
build(tmp1, [i1, i2, i3, i4])

# Loop interchanges
interchange(i4, i3)
interchange(i4, i2)
interchange(j1, j2)
interchange(k3, k2)

# Transpositions
tmp2t = vtranspose(tmp2, 1, 2)
replace_array(j3, tmp2, tmp2t)
tmp3t = vtranspose(tmp3, 1, 3)
replace_array(k4, tmp3, tmp3t)

# ... other optimizations
```

### Example of assessment: Different heuristics of loop interchanges (+ parallelization)

- Variant L1: Loop interchanges only;
- Variant L2: Loop interchanges + data transpositions with copying;
- Variant L3: Loop interchanges + data transpositions without copying.

Baseline: sequential execution (3.32s). Machine: 24-core Intel(R) Xeon(R) CPU E5-2680 v3 @ 2.50GHz (Haswell)

### Future Work

- Applications to other domains
- Syntax refinement
- Formal semantics

This work was partially funded by the German Research Council (DFG) through the Cluster of Excellence ‘Center for Advancing Electronics Dresden’ (cfaed) and by PSL Research University through the ACOPAL project.